Course code	Course Name	L-T-P - Credits	Year of Introduction
MR301	Linear Control Systems	3-1-04	2016
Prerequisite : I	NIL		

- To give knowledge on automatic control systems and their applications in designing of mechatronics system.
- To provide knowledge about the stability analysis of control systems.
- To impart knowledge on the Mathematical modelling and analogy of different systems.

Syllabus

Principle of Automatic control- Open loop and closed loop systems- block diagram reduction signal flow graphs - Mason's gain formula- Modeling of translational and rotational mechanical systems- force voltage & force-current analogy - toque-voltage & torque-current analogy- Time domain analysis- time domain specifications- Concept of stability- Routh-Hurwitz stability criterion- Root Locus Method- Frequency Domain Analysis- polar and Bode Plots- Nyquist Stability Criterion- PI, PD and PID controllers- Lead, Lag and Lead- Lag compensation-Case study of automatic control system.

Expected outcome.

The students will be able to

- Understand the system modeling and analogous circuits.
- Understand the concept of stability analysis in control systems using different plots
- Get knowledge in P, PI and PID controllers and compensation in control systems.
- Get knowledge in time domain analysis.
- Get knowledge on the role of control system in mechatronics with suitable case studies.

Text Book:

1. Nagrath & Gopal, Control Systems Engineering, New Age International (P) Limited

- 2. Katsuhiko Ogata, Modem Control Engineering, Pearson Education.
- 3. A. Nagoorkani, *Control Systems*, RBA Publications

References:

- 1. Kuo, Automatic Control Systems, Prentice Hall
- 2. Norman S. Nise, Control Systems Engineering, Wiley India Pvt. Ltd.
- 3. S. Palani, Control Systems Engineering, Tata McGraw Hill
- 4. K. Ogata, Discrete- Time Control Systems, Pearson Education
- 5. A. Anand Kumar, Control Systems, PHI

	Course Plan				
Module	Contents	Hours	Sem. Exam Marks		
I	Principle of Automatic control- Open loop and closed loop systems – examples System modeling & approximations - modeling of electrical systems – dynamic equations using KCL & KVL of RL, RC and RLC circuits - development of block diagrams of electrical networks - block diagram reduction - signal flow graphs - Mason's gain formula.	9	15%		

II	Modeling of translational and rotational mechanical systems – differential equations for mass, spring, dashpot elements - D'Alembert's principle – dynamic equations & transfer function for typical mechanical systems - analogous systems – force voltage & force-current analogy - toque-voltage & torque-current analogy – electromechanical systems - transfer function of armature controlled dc motor & field controlled dc motor.	9	15%
	FIRST INTERNAL EXAMINATION	V1	1
III	Time domain analysis – continuous systems -standard test signals - step, ramp, parabolic, impulse - transient and steady state response –first order systems - unit impulse, step & ramp responses of first order systems - second order systems unit step response- under damped and over damped systems - time domain specifications - steady state error – static position, velocity & acceleration error constants.	9	15%
IV	Concept of stability - stability & location of the poles in S- plane - Routh-Hurwitz stability criterion-Root Locus Method- Construction of root locus- Effect of poles and zeros and their location on the root locus.	10	15%
	SECOND INTERNAL EXAMINATION		
V	Frequency Domain Analysis- Frequency Response representation- Polar Plot- Logarithmic Plots-Frequency Domain Specifications - Non-Minimum Phase Systems- Transportation	9	20%
VI	Need for Cascade compensation-Cascade Compensation- PI, PD and PID controllers – tuning of PID Controller- Lead, Lag and Lead- Lag compensation- Role of control system in mechatronics-case studies Automatic temperature control- automatic traffic light control-Automatic street light control.	10	20%

END SEMESTER EXAM

QUESTION PAPER PATTERN

100 Maximum Marks :

Exam Duration:3 hours

PART A: FIVE MARK **QUESTIONS PART A**: FIVE MARK QUESTIONS 8 compulsory questions –1 question each from first four modules and 2 questions each from

(8 x 5 = 40 marks)

PART B: 10 MARK QUESTIONS

last two modules

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

(3 x10 = 30 marks)

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

Course co	ode	Course Nar	ne	L-T-P - Credit	ts Ind	Year of
MR30	3	Microprocessors and Mi	icrocontrollers	3-0-03		2016
Prerequis	site •]		ci oconti oners	5-0-05		2010
Course O	bioct					
• To	study	the Architecture of micro	processor 8086 &	& microcontroller	8051	
• To	study	the addressing modes & i	instruction set of	8086 & 8051.		
• To	intro	luce the need & use of Int	errupt structure 8	086 & 8051.		
	1	API ABL	IUL K	alan	1	
Syllabus		TOUR	ala	ADIC	1	
Architectu Maximum Programm 8253- pro DMA Cor	n mo nable gram	Intel 8086 processor – Pin le –Timing diagrams – Peripheral interface (8255 nable interrupt controller r 8237-Introduction to em	- DMA-8086 A - DMA-8086 A 5) – Mode 0,1,2 8259- Programn ibedded controlle	ddressing modes operations- Inter nable communica rs- architectures-	: Minimui s – Instr val timer tion Interf	n mode and ruction set- application face (8251)- on to 8051-
8051 fam	ily a	chitecture of 8051 -pin	details- port op	eration- memory	organizat	tion- SFRs-
programm	ing i	assembly - assembler d	irectives- addres	sing modes- instr	uction set	- timer and
counter o	perat	ons- interrupts- serial c $\sqrt{0.8255}$ external memor	ommunication-	introduction to f	ardware	otor- DAC-
ADC- mat	trix k	vboard.	y- seven segmen	it display- LCD-	stepper m	0101- DAC-
Expected	d out	ome.				
Student w	vill g	in knowledge on micropro	ocessor and micro	ocontrollers based	system de	esign
Text Boo	ok:	100				
1. A.K. Ro	oy, K.	M. Bhurchandi, Advanced	' Mic <mark>r</mark> oprocessors	s and Peripherals	McGraw-	Hill
Internation	nal					
2. Muham	mad .	Ali Mazidi, Janice Gillipse	Mazidi, Rolin D	. Mckinlay, "805.	l Microco	ntroller and
Embedded	l Syst	ms Using Assembly and C	Pearson Educa	tion, 2010		
1. Douglas	s V H	all, Microprocessors And I	Interfacing Progr	amming and Hard	<i>dware</i> Tat	a McGraw-
2. N.Sent	hil K	umar, M.Saravanan, S.Je	evananthan, "M	icroprocessors an	nd Microo	controllers",
Oxford,20	013.		Esta,			
			Course Plan			
Module		Co	ntents		Hours	Sem. Exam Marks
Ι	Arc Arc cont bus mec DM	itecture of 8086 itecture of Intel 8086 pro igurations: Minimum mod timing - Timing diag nanism – Types and pri A.	2014 ocessor – Pin des le and Maximum grams – Interru ority – Interrupt	mode –system pts: Interrupt vector table-	8	15%
Π	Pro 808 Instr Arit Proc	Addressing modes – I octions – String Instruct ametic Instructions – tr essor control instructions ersion-searching –Sorting	nstruction set – tions – Logical ransfer control s- Arithmetic ope	Data transfer Instructions – Instructions – erations- Code	6	15%

FIRST INTERNAL EXAMINATION				
III	8086 interface Programmable Peripheral interface (8255) – Mode 0,1,2 operations- Interval timer application 8253- programmable interrupt controller 8259- Programmable communication Interface (8251)- DMA Controller 8237.	8	15%	
IV	Architecture of 8051 Overview of 8051 microcontrollers – Architecture – Assembly programming –data types and directives –flag bits – register banks and stack.		15%	
	SECOND INTERNAL EXAMINATION	1		
V	Programming 8051 8051Addressing modes – Instruction set -loop and Jump instructions – call instructions – Arithmetic and Logic instructions and simple programs – 8051 interrupts – programming timer interrupts.	7	20%	
8051 interface Interfacing of microcontroller – External memory interfacing- VI LCD and Keyboard interfacing – Parallel and serial ADC interfacing – DAC interfacing – Interfacing 8255 - Stepper motor control – DC motor interfacing.				
END SEMESTER EXAM				

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK **QUESTIONS**

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules $(8 \times 5 = 40 \text{ marks})$

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

Estr

(3 x 10 = 30 marks)

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

Course No.	Course Name	L-T-P - Credits	Year of			
			Introduction			
MR305	PLC and Data Acquisition Systems	3-0-03	2016			
Prerequisite : NIL						

• To provide students the fundamentals of PLC and Data acquisition systems

Syllabus

Need of computer in a control system-Functional block diagram of a computer control system-Data loggers- Supervisory computer control- Direct digital control-Digital control interfacing-SCADA. DACs-Basic DAC Techniques-Types of DAC - ADCs – Types of ADC-Comparison of A/D conversion techniques-DAC/ADC specifications -Isolation amplifiers. Sampling theorem – Sampling and digitizing – Aliasing – Sample and hold circuit– Definition- design and need for data acquisition systems – Interfacing ADC and DAC with Microprocessor / Multiplexer -Multiplexed channel operation –Microprocessor/PC based acquisition systems. Basics of PLC-Advantages- Capabilities of PLC- Architecture of PLC- Scan cycle- Types of PLC- Types of I/O modules- Configuring a PLC- PLC wiring-Simple process control programs using Relay Ladder Logic - PLC arithmetic functions - Timers and counters –data transfer-comparison and manipulation instructions- PID instructions- PTO / PWM generation. Requirement of communication networks of PLC – connecting PLC to computer – Interlocks and alarms Need for HMI systems. Types of HMI- interfacing PLC to HMI.

Expected outcome

- Students will understand the basics of data conversion and data acquisition systems
- Students will acquire proficiency in programming programmable logic circuits.

Text Books:

1 Curtis D. Johnson Process Control Instrumentation Tech 8TH Edition Prentice Hall June 2005.

2. Petrezeulla, Programmable Controllers, McGraw Hill, 1989.

3. D.Roy Choudhury and Shail B.Jain, Linear Integrated circuits, New age International Pvt .Ltd, 2003.

4.John W Webb & Ronald A Reis, "Programmable logic controllers: Principles and Applications", Prentice Hall India, 2003.

References:

1. G.B.Clayton, *Data Converters* The Mac Millian Press Ltd., 1982.

2. Hughes .T, Programmable Logic Controllers, ISA Press, 1989.

3. Bolton W., "Mechatronics", Pearson Education, 2009

4. Prof. Rajesh Mehra, Plcs & Scada - Theory And Practice, Laxmi Publication

Course Plan				
Module	Contents	Hours	Sem. Exam Marks	
I	Computer Control -Introduction Need of computer in a control system-Functional block diagram of a computer control system-Data loggers- Supervisory computer control- Direct digital control-Digital control interfacing-SCADA.	7	15%	
Π	Data Converters DACs-Basic DAC Techniques-Weighted Resistor- R-2R Ladder and Inverted R-2R ladder type DACs- ADCs –	7	15%	

	Parallel ADC- Dual slope ADC- Successive Approximation		
	ADC-Comparison of A/D conversion techniques- DAC/ADC		
	specifications - Typical IC's for DAC- ADC - Isolation		
	amplifiers.		
	FIRST INTERNAL EXAMINATION		
	Data Acquisition Systems		
	Sampling theorem – Sampling and digitising – Aliasing –		
III	Sample and hold circuit– Definition- design and need for data acquisition systems – Interfacing ADC and DAC with Microprocessor / Multiplexer - Multiplexed channel operation	$\sqrt{7}$	15%
	-Microprocessor/PC based acquisition systems.	1	
	Programmable Logic Controllers		
IV	Basics of PLC- Advantages- Capabilities of PLC- Architecture	7	15%
1 V	of PLC- Scan cycle- Types of PLC- Types of I/O modules-	/	1370
	Configuring a PLC- PLC wiring.		
	SECOND INTERNAL EXAMINATION		•
	PLC Programming		
	Simple process control programs using Relay Ladder Logic -		
V	PLC arithmetic functions - Timers and counters -data transfer-	7	20%
	comparison and manipulation instructions- PID instructions-		
	PTO / PWM generation.		
	PLC Communication and HMI		
	Requirement of communication networks of PLC – connecting	_	
VI	PLC to computer – Interlocks and alarms	7	20%
	HMI -Need for HMI systems- Types of HMI- interfacing PLC to HMI.		
1	END SEMESTER EXAM		

Maximum Marks : 100 PART A: FIVE MARK QUESTIONS Exam Duration:3 hours

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5= 40 marks)

Estd.

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

(3 x10 = 30 marks)

Course N	No. Course Name	L-T-P - Credits		Year of
			Int	roduction
MR30'	7 Thermodynamics	3-0-03		2016
Prerequis	ite : NIL			
Course O	bjectives			
• To	impart knowledge on the basic concepts of the	rmodynamics		
Syllabus			_	
Basic con	cepts and definitions -Zeroth law of thermody	mamics – measurer	nent of te	emperature-
Different	forms of energy- Stored energy and transitio	n energy- work an	d heat- F	First law of
thermodyn	namicsSecond law of thermodynamics – reven	sibility and irrevers	ibility- Ca	arnot cycle-
Carnot's t	heorem. Entropy- Clausius' theorem- Clausiu	s' inequality- Entro	py princi	ple and its
application	ns- Available energy- Law of degradation	of energy- useful	work-	dead state-
Availabilit	y- Gibb's and Helmholtz function- See	cond law efficien	ncyThire	d law of
thermodyr	namics. Thermodynamic relations – Maxwell's	Equations- Tds equ	lations- Jo	oule Kelvin
effect- Cla	usius –Clapeyron equation -Psychrometrics			
Expected	autcome		_	
• Sti	idents will gain knowledge on the concept of	thermodynamics ar	nd the psy	vchrometric
pro	operties of atmospheric air.	thermodynamics an	id the psy	yemometrie
Text Boo	k:			
1. P.K.Na	g, Thermodynamics, Tata Mc Graw Hill, 4th edi	ition		
2. Kothan	daraman. C.P., Domkundwar. S. & Domkundwa	ar. A.V., "A course i	in Therma	ıl
Engineerin	ng" Dhanpatrai & Co (P) Ltd, Fifth edition, 200	0.		
Reference	ces:			
1. Michael	A. Boles, Yunus A. Cengel, Yunus <mark>C</mark> engel, "Th	nermodynamics", 2n	d Edition	, Mc Graw
Hill India,	2006.			
2. Holman	.J.P., "Thermodynamics", 3rd Ed. McGraw-Hil	l, 2000.		
	Course Plan	n	_	C
Module	Contents		Hours	Marks
	Basic concepts and definitions – Ma	croscopic and		
	microscopic approach- Continuum concep	t- system and		
	control volume- properties- processes and cy	cles- Method of		
Ι	checking of properties- Quasi-static process	- homogeneous	7	15%
	and heterogeneous systems- thermodynam	ic equilibrium-		
	Zeroth law of thermodynamics – measurement	t of temperature-		
	Temperature scales- Concept of absolute temp	erature scale.		
	Different forms of energy-Stored energy	and transition		
	energy- work and neat- different types of wor	rk transfer- pov		
II	work- indicator diagram- Free expansion-	First law of	7	15%
	thermodynamics- Joule's experiment-First la	w applied for a		
	Jouie's law- PMIMI EIDST INTEDNAL EVAN			
	FIRST INTERNAL EXAM			
	anging Kalvin Plank and Clausius' etc	tement DMM2		
ш	refrigerator and heat nump- reversibility and	d irreversibility	7	15%
111	Causes of irreversibility-types of irreversibility	ty- Carnot cycle-	/	1.570
	Carnot's theorem.			

IV	Entropy- Clausius' theorem- Clausius' inequality- Entropy principle and its applications- Available energy-Law of degradation of energy- useful work- dead state- Availability- Gibb's and Helmholtz function-Second law efficiency	7	15%
	SECOND INTERNAL EXAMINATION		
V	Third law of thermodynamics-Thermodynamic relations – Maxwell's Equations- Tds equations- Joule Kelvin effect- Clausius –Clapeyron equation	7	20%
VI	Psychrometrics - Properties of atmospheric air- Psychrometric properties – dry bulb temperature- wet bulb temperature and dew point temperature- specific humidity- relative humidity- degree of saturation-use of psychrometric chart- simple problems.	7	20%
END SEMESTER EXAM			

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5 = 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

(3 x10 = 30 marks)

Course No.	Course Name	L-T-P-Credits	Year of Introduction	
ME220	MANUFACTURING TECHNOLOGY	3-0-0-3	2016	
Prerequisite:	Nil	-		
Course Object 1. To give a 2. To provid 3. To famili 4. To give a 5. To introd allied may 6. To give a metal join	etives:- n exposure to different techniques of casting le an exposure to different rolling processes arize with different forging methods, caution n introduction to various work and tool hold uce to the bending, shearing and drawing p chines, an understanding of welding metallurgy and hing techniques.	g and molds required. and different rolled put is to be adopted in die ing devices used in m processes of sheet me i weldability and to in	roducts design. anufacturing. etal working and ntroduce various	
SYLLABUS Casting –patte Rolled parts- Extrusion Def of Clamp -Sh Weldability – Weldability – Welding -Arc Brazing- Sold	erns - Cores – Gating – Risering – Defec forging – Coining – Heading – Piercing ects – Drawing Process -Principles of Loca leet metal characteristics –Deep drawing – Solidification of Weld Metal – Heat Affe Welding - Ultrasonic Welding – Friction ering.	ets in Castings - Rol g –Die Design– Ext tion–Principles of Cl –Spinning–Definitio ected Zone – Weldin n Welding – Resista	ling –Defects in rusion Process– amping – Types n of Welding – g Defects - Gas nce Welding –	
 Expected outcomes: At the end of the course the students will be able to 1. Acquire knowledge in various casting processes and technology related to them. 2. Understand the rolling passes required for getting required shapes of rolled products. 3. Discuss important aspects of forging techniques 4. Discuss sheet metal working processes and their applications to produce various shapes and products. 5. Acquire knowledge in various types of welding processes. 				
Text books:- 1. Amital West H 2. S.Kalp Pearso Reference boo 1. RAO, 2. RAO, 3. Cyril I 4. Handle 5. Camp Hill, 19	oha Ghosh and Ashok Kumar Mallick, Manu Press Ltd, New Delhi, 2002 akjian and Steven R Schimid, Manufacturin n,2001 oks:- Manufacturing Technology-Vol 2 3e, McGr Manutacturing Technology-Vol 1 4e, McGr Donaldson and George H LeCain, Tool Desi pook of Fixture Design – ASTME bell J. S., Principles of Manufacturing Mater 999	ufacturing Science Af g Engineering and Te aw Hill Education Ind aw Hill Education Ind ign,TMH rials and Processes, Ta	filiated East chnology, lia, 2013 lia, 2013 ata McGraw	

- 6. P R Beeley, Foundry Technology, Elsevier, 2001
- 7. Richard W. Heine, Carl R. Loper, Philip C. Rosenthal, Principles of Metal Casting,

- Tata McGraw-Hill Education, 2001
- 8. Paul Degarma E and Ronald A. Kosher ,Materials and Processes in Manufacturing, Wiley,20111
- 9. P. N. Rao, Manufacturing Technology Foundry, Forming and Welding, Tata McGraw-Hill Education, 2011
- 10. HMT Production Technology, 1e McGraw Hill,2001



Course Plan				
Module	Contents	Hours	Semester Examination Marks	
	Sand Casting – Sand Molds-Types of Molding Sands and Testing	1		
	Type of patterns - Pattern Materials	1		
	Cores –Types and applications –Sand Molding Machines	1		
т	Gating System – Risering	1	150/	
1	Shell Mold Casting – Ceramic Mold Casting	1	13%	
	Investment Casting – Vacuum Casting – Slush Casting	1		
	Pressure Casting – Die Casting – Centrifugal Casting	1		
	Design Considerations based on Various Shapes - Defects in Castings – simple problems in casting	1		
	Principles of Rolling –Types of rolling mills, Mechanics of Flat Rolling	1		
	Roll Force and Power Requirement - Neutral Point	1	15%	
П	Hot and Cold Rolling	1		
	Defects in Rolled Plates - Rolling Mills	1		
	Ring Rolling – Thread Rolling	1		
	Applications- Rolling of tubes, wheels, axles and I-beams	1		
	FIRST INTERNAL EXAM			
	Classification of forging – Forging methods – Forging under sticking condition	1		
	Precision Forging – Coining – Heading – Piercing	1		
III	Die Design:- Preshaping, Design Features, Draft Angles – Die Materials and Lubrication	1	15%	
	Forging Machines – Forging Defects and tests	1		
	Extrusion Process - Hot Extrusion – Cold Extrusion	1		
	Impact Extrusion – Extrusion Defects – Drawing Process, wire drawing process	1		

	Principles Location - Degrees of Freedom, 3-2-1 principle of locating	1	
	Locating from Planes - Locating from Circular Surfaces	1	
IV	Concentric Locating - Principles of Clamping	1	15%
	Types of Clamps - Strap Clamps Slide Clamps - Swing Clamps - Hinge Clamps	1	
	Vacuum Clamping - Magnetic Clamping	1	
	SECOND INTERNAL EXAM		
	Sheet metal characteristics – Typical shearing	1	
	Bending Sheet and Plate – Spingback - Bending Force	1	
	Press Brake Forming - Tube Bending	1	
	Stretch Forming - Deep Drawing	1	
V	Rubber forming - Spinning Shear Spinning - Tube Spinning	1	20%
	Definition of Welding - Weldability – Solidification of the Weld Metal	1	
	Heat Affected Zone – correlation of strength of welded joint with structure - Welding Defects	1	
	Gas Welding: – Flame Characteristics	1	
	Equipment, fluxes and filler rods	1	
	Arc Welding – Applications and Equipment	1	
	Electrodes	1	
VI	Shielded Metal Arc Welding – Submerged Arc Welding	1	20%
VI	GTAW – Plasma Arc Welding	1	2070
	Ultrasonic Welding – Friction Welding	1	
	Resistance Spot Welding	1	
	Resistance Seam Welding – Stud Welding – Percussion Welding - simple problems in welding	1	
	Brazing:- Filler Metals, Methods - Soldering:- Techniques, Types of Solders and Fluxes	1	
	END SEMESTER EXAM		

Question Paper Pattern

Total marks: 100, Time: 3 hrs

The question paper should consist of three parts

Part A

4 questions uniformly covering modules I and II. Each question carries 10 marks Students will have to answer any three questions out of 4 (3X10 marks = 30 marks)

Part B

4 questions uniformly covering modules III and IV. Each question carries 10 marks Students will have to answer any three questions out of 4 (3X10 marks =30 marks)

Part C

6 questions uniformly covering modules V and VI. Each question carries 10 marks Students will have to answer any four questions out of 6 (4X10 marks =40 marks)

Note: In all parts, each question can have a maximum of four sub questions, if needed.



Course code	Course Name	L-T-P- Credits	Year of Introduction		
ME369	Tribology	3-0-0-3	2016		
	Prerequisite : Nil	1			
Course Objectives		ΙΛΛ	Attachural anisal		
• 10 provide bi	road based understanding of the subject 1ri	bology and	its technological		
To understand and the effect	d the genesis of friction, the theories/laws of control of viscosity	sliding and r	olling friction		
• To learn about wear problem	it consequences of wear, wear mechanisms,	wear theories	and analysis of		
To learn abou hydrodynami	It the principles of lubrication, lubrication re c and the advanced lubrication techniques and model working	gimes, theorind the application	es of tion of		
To understand knowledge ab	d the importance of adhesion property in different bearing materials.	ferent applica	tions and to get		
• To understand surface chara	d the nature of engineering surfaces, their to cterization techniques	pography and	learn about		
Syllabus					
Introduction to Tribolo Like Friction, Wear and measurement of friction Surfaces, surface mo Recording Systems, Typ	gy- Tribology in Design, Tribology in Indu d Lubrication, different types of lubrication n and wear -The Topography of Engineerin dification techniques- Adhesion properti pes of Bearings, Comparison of Sliding and	stry, Tribolo techniques ang Surface, C es, Adhesio Rolling Cont	gical Parameters and applications, Contact Between n in Magnetic act Bearings.		
Expected Outcome					
The students w <mark>ill be a</mark>	ble to				
i. Understand the	subject 'tribology' and its technological sign	ificance.			
ii. Understanding t iii. Get basic idea o wear problems	he theories/laws of sliding and rolling friction n consequences of wear, wear mechanisms,	on and the effe wear theories	ect of viscosity. and analysis of		
iv. Get an exposure and the application	to theories of hydrodynamic and the advance on of lubrications in metal working.	ed lubricatio	n techniques		
v. Gain overview of different bearing	v. Gain overview of adhesion property in different applications and to get knowledge about different bearing materials				
vi. Get basic idea about the nature of engineering surfaces, their topography and learn about surface characterization techniques.					
Text books					
 Ernest Rabinowicz, Friction and Wear of Materials, John Wiley & sons, 1995 I.M. Hutchings, Tribology: Friction and Wear of Engineering Materials, Butterworth- Heinemann, 1992 Prasanta Sahoo, Engineering Tribology, PHI Learning Private Ltd. New Delbi, 2011 					

Reference books

- 1. B. Bhushan, Introduction to Tribology, John Wiley & Sons, Inc, New York, 2002
- 2. B.Bhushan, B.K. Gupta, Handbook of tribology: materials, coatings and surface treatments", McGraw-Hill,1997
- 3. Halling J, "Principles of Tribology", McMillan Press Ltd., 1978

	Course Plan			
Module	TECH Contents	Hours	End Sem. Exam. Marks	
	Introduction to Tribology- Tribology in Design, Tribology in Industry, Economic Aspects of Tribology	1		
	Tribological Parameters Like Friction, Wear and Lubrication	1		
Ι	The Topography of Engineering Surface, Contact Between Surfaces.	2	15%	
	Types of Bearings, Comparison of Sliding and Rolling Contact Bearings.	2		
	Introduction, Empirical Laws of Friction, Kinds of Friction	1		
	Causes of Friction, Theories of Friction	1		
тт	Measurement of Friction			
11	Polling Eriction Laws of Polling Friction Polation Patwoon	<u>_</u>	15%	
	Temperature and Friction	1		
	Stick-Slip Prevention of Stick-Slip Consequences of Friction	1		
FIRST INTERNAL EXAMINATION				
	Types of Wear, Various Factors Affecting Wear			
	Theories of Wear, Wear Mechanisms			
	Measurement of Wear.		l	
III	Wear Regime Maps, Alternative Form of Wear Equations		15%	
	Lubricated and Unlubricated Wear of Metals, Materials Used in Different Wear Situations.	2		
	Fundamentals of Viscosity And Viscous Flow	1		
IV	Principle and Application of; Hydrodynamic Lubrication, Elastrodynamic Lubrication, Boundary and Solid Lubrication	2	15%	
1,	Types of Lubricants, Properties of Lubricants	1		
	Effect of Speed and Load on Lubrication, Frictional Polymers.	1		
	Lubrication in Metal Working: Rolling, Forging, Drawing and	2		
Extrusion.				
	Adhesion: Introduction Adhesion Effect by Surface Tension			
V	Purely Normal Contact and Compression Plus Shear	2	20%	

	Adhesion in Magnetic Recording Systems	1		
	Dependence of Adhesion on Material and Geometric Properties.			
	Bearing Materials : Introduction, Rolling Bearing, Fluid Film Lubricated Bearing, Dry Bearing, Bearing Constructions.	3		
	Introduction To Surface Engineering, Concept and Scope of Surface Engineering.	4		
V1	Surface Modification – Transformation Hardening, Surface Melting, Thermo chemical Processes	3		
	Surface Coating – Plating and Anoding Processes, Fusion Processes, Vapor Phase Processes.	3	20%	
	Selection of Coating For Wear And Corrosion Resistance, Potential Properties and Parameters of Coating.	1		
END SEMESTER EXAMINATION				

Question Paper Pattern

Maximum marks: 100

The question paper should consist of three parts

Part A

There should be 2 questions each from module I and II Each question carries 10 marks Students will have to answer any three questions out of 4 (3X10 marks = 30 marks)

Part B

There should be 2 questions each from module III and IV Each question carries 10 marks Students will have to answer any three questions out of 4 (3X10 marks =30 marks)

Part C

There should be 3 questions each from module V and VI Each question carries 10 marks Students will have to answer any four questions out of 6 (4X10 marks =40 marks)

Note: Each question can have a maximum of four sub questions, if needed.

Time: 3 hrs

Course code	Course Name	L-T-P - Credits	Year of
			Introduction
MR361	Reliability Engineering	3-0-03	2016
Prerequisite :	NIL	·	

• To understand the basic principle of reliability engineering and its applications to various systems in engineering

Syllabus

Probability - Probability distributions --central tendency and dispersion- point estimation and interval estimation- goodness of fit tests-Reliability -Failure data analysis- reliability functions-hazard functions- Availability and Maintainability -Reliability hazard models - distribution functions and reliability analysis System Reliability - Different configurations – Redundancy – m/n system – Complex systems- Standby system. Interference theory and reliability computations – Maintainability prediction – Measures of maintainability – System Availability – Replacement theory

Expected outcome.

On completion of this subject students will be able to

• Understand the various concepts of reliability and quality in the field of engineering

Text Books:

- 1. Naikan A., Reliability Engineering and Life Testing, PHI, New Delhi, 2010
- 2. O'Connor PDT, Practical Reliability Engineering, John Wiley & Sons Ltd, Singapore, 2004

Data Book (Approved for use in the examination): Statistical Table

References:

1. Lewis, E.E., Introduction to Reliability Engineering, John Wiley & Sons, 1995.

- 2. Modarres, Reliability and Risk analysis, Mara Dekker Inc., 1993.
- 3. Kapur K.C. and Lamberson L.R., Reliability in Engineering Design, John Wiley & Sons, 1977

Course Plan				
Module	Contents	Hours	Sem. Exam Marks	
I	Probability Probability: Conditional probability- Probability distributions – Normal- Exponential and Weibull distributions – relationship between them and their significance -central tendency and dispersion- point estimation and interval estimation- goodness of fit tests.	7	15%	
П	Reliability Reliability: Definitions- Importance- Quality and reliability- bath tub curve -Failure data analysis- Hazard rate- failure rate- MTTF- MTBF- reliability functions- hazard functions- Availability and Maintainability	7	15%	
FIRST INTERNAL EXAMINATION				
III	Failure data analysis Reliability hazard models- Parts stress model- Constant- linearly increasing and time dependent failure rates- Weibull	7	15%	

	model- distribution functions and reliability analysis System Reliability: System configurations- series- parallel- mixed configurations- k out of m system- standby systems		
IV	Reliability assessment Different configurations – Redundancy – m/n system – Complex systems: RBD – Baye's method – Cut and tie sets – Fault Tree Analysis – Standby system.	7	15%
	SECOND INTERNAL EXAMINATION		
V	Reliability monitoring Interference theory and reliability computations – Normal- exponential and Weibull stress – strength Distributions Life Testing – Objectives- Types - Censoring- replacement- accelerated life testing – data quantification – Temperature stress and failure rates – stress combinations	7	20%
VI	Reliability improvementAnalysis of downtime – Repair time distribution – SystemMTTR – Maintainability prediction – Measures ofmaintainability – System Availability – Replacement theory	7	20%
	END SEMESTER EXAM		

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5= 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

(3 x10 = 30 marks)

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

2014

 $(2 \times 15 = 30 \text{ marks})$

Course N	Ko. Course Name	L-T-P - Credits	i Int	Year of	
MR36	3 OBJECT ORIENTED PROGRAMMING	3-0-03	1111	2016	
Prerequis	ite : NIL			2010	
Course O	bjectives				
	• To understand the concepts of object-orie	ented programming an	nd master	OOP using	
	C++.				
Syllabus Object oriented programming concepts - Introduction to C++ - classes – access specifiers - function and data members - default arguments - function overloading - friend functions const and volatile functions - static members -Objects - pointers and objects - constant objects – nested classes - local classes-Constructors - destructors - Operator overloading - Function and class templates - Exception handling -Inheritance - Streams and formatted I/O - I/O manipulators - file handling - random access - object serialization - namespaces - std namespace - ANSI String Objects - standard template library.					
Ехрессе	 Familiarity with the concepts of object-o Oriented Programming using C++. 	riented programming	g and mas	ter Object	
Text Boo 1. B. Triv	k: redi, "Programming with ANSI C++", Oxford	University Press, 200)7.		
1 Ira Po Reprint20 2. S. B. Education 3. B. Stro	hl, "Object Oriented Programming using C 004. Lippman, Josee Lajoie, Barbara E. Moo, n,2005. Dustrup, "The C++ Programming language", T	++", Pearson Educat "C++ Primer", Fou hird edition, Pearson	tion, Seco rth Editio Education	ond Edition on, Pearson 1, 2004.	
	Course Pl	an			
Module	Contents		Hours	Sem. Exam Marks	
Ι	Object oriented programming concepts - or methods and messages - abstraction and inheritance - abstract classes - polymorphis C++ - classes - access specifiers - function a default arguments - function overloading - const and volatile functions - static members	objects - classes - d encapsulation - sm. Introduction to and data members - friend functions -	7	15%	
П	Objects - pointers and objects - constant classes - local classes-Constructors - defa Parameterized constructors - Constructo allocation - copy constructor - destructors.	objects - nested ault constructor - r with dynamic	7	15%	
	FIRST INTERNAL EXA	MINATION		·	
III	Operator overloading - overloading through overloading the assignment operator - to explicit constructor.	t friend functions - type conversion -	7	15%	

IV	Function and class templates - Exception handling - try-catch- throw paradigm - exception specification - terminate and Unexpected functions - Uncaught exception.	7	15%
	SECOND INTERNAL EXAMINATION		
V	Inheritance - public, private, and protected derivations - multiple inheritance - virtual base class - abstract class - composite objects Runtime polymorphism - virtual functions - pure virtual functions - RTTI - typeid - dynamic casting - RTTI and templates - cross casting - down casting .	7	20%
VI	Streams and formatted I/O - I/O manipulators - file handling - random access - object serialization - namespaces - std namespace - ANSI String Objects - standard template library.	7	20%

END SEMESTER EXAM

QUESTION PAPER PATTERN

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5= 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

uestions ($3 \times 10 = 30$ marks)

1.1.1

Course code	Course Name	L-T-P - Credits	Year of		
			Introduction		
**341	DESIGN PROJECT	0-1-2-2	2016		
Prereguisite : Nil					

- To understand the engineering aspects of design with reference to simple products
- To foster innovation in design of products, processes or systems
- To develop design that add value to products and solve technical problems

Course Plan

Study :Take minimum three simple products, processes or techniques in the area of specialisation, study, analyse and present them. The analysis shall be focused on functionality, strength, material, manufacture/construction, quality, reliability, aesthetics, ergonomics, safety, maintenance, handling, sustainability, cost etc. whichever are applicable. Each student in the group has to present individually; choosing different products, processes or techniques.

Design: The project team shall identify an innovative product, process or technology and proceed with detailed design. At the end, the team has to document it properly and present and defend it. The design is expected to concentrate on functionality, design for strength is not expected.

Note : The one hour/week allotted for tutorial shall be used for discussions and presentations. The project team (not exceeding four) can be students from different branches, if the design problem is multidisciplinary.

Expected outcome.

The students will be able to

- i. Think innovatively on the development of components, products, processes or technologies in the engineering field
- ii. Analyse the problem requirements and arrive workable design solutions

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Reference:

Michael Luchs, Scott Swan, Abbie Griffin, 2015. Design Thinking. 405 pages, John Wiley & Sons, Inc

Evaluation

First evaluation (Immediately after first internal examination)20 marksSecond evaluation (Immediately after second internal examination)20 marksFinal evaluation (Last week of the semester)60 marks

Note: All the three evaluations are mandatory for course completion and for awarding the final grade.

Course code	Course Name	L-T-P - Credite	Year of			
MR331	Microprocessors and Microcontrollers lab	0-0-3:1	2016			
Prerequisite:	MR303 Microprocessors and microcontrollers		2010			
Course Objec	tives					
To enal	ole students to do basic programming in the micro	processors and n	nicrocontrollers.			
List of Exercis 8086 program 1. 8086 kit fam	ses/Experiments : ming using kits / MASM(Any 6) niliarization.	LAM				
2. Basic arithm	netic and Logical operations	ICAL				
3. Square, Squ	are root and Cube program	V				
4. Data transfe	r program	1				
5. Programmin	g exercise using BCD and Hexadecimal numbers					
6. Programmin	g exercise : sorting ,searching and string					
7. Interfacing v	vith A/D and D/A converters					
8. Interfacing v	vith stepper motors					
9. IBM PC pro	gramming : Basic programs using DOS and BIOS	5 interrupts				
8051 programmers 8051 p	ning using kits (Any 6) 1 subtraction of 8 bit numbers a <mark>nd</mark> 16 bit numbers					
2. Multi byte a	ddition					
3. Programs or	Data Transfer Instructions					
4. Square, Squ	are root and Cube program					
5. 8 bit multipl	ication and division					
6. Interfacing v	with A/D and D/A converters					
7. Waveform g	eneration using 8051					
7. Interfacing v	with stepper motors					
8. Parallel inter	rfacing –LCD 2014					
Expected out	tcome.					
On completion	of the course the student will be able basic arithmetic and logical calculations on 8086	and 8051 proces	sors			
2. To understar	1. 10 carry out basic arithmetic and logical calculations on 8086 and 8051 processors 2. To understand the interface of 8086 and 8051 processors with external devices					
3. To understar	id the applications of microprocessors and microc	controller based s	ystem			
Text Book:			2			
1. A.K. Roy, K	A.M. Bhurchandi, Advanced Microprocessors and	Peripherals McO	Graw- Hill			
International		1 (0071)5	. 77 *			
2. Muhammad	All Mazidi, Janice GillipseMazidi, Rolin D. Mclitans Using Assembly and C" Paperson Education	anlay, "8051 Mi	crocontroller and			
Embedded Syst	tems Using Assembly und C Featson Education,	2010				

Course code	Course Name	L-T-P - Credits	Year of
MR333	Metrology and PLC Lab	0-0-3-1	2016
Prerequisite:	MR305 PLC and data acquisition systems		2010
Course Object	tives		
•	To provide students hands on experience of	on measuring instrument	s and PLC
List of Exercis	ses/Experiments : (Minimum 12 experim	ents are mandatory)	
1. Strai	n gauge characteristics	ZATAM	
2. load	cell characteristics	ALAN	
3. LVD	T characteristics	GICAL	
4. Char	acteristics of thermocouples	UICAL	
5. Char	racteristics of RTD	IIY	
6. Char	acteristics of thermostats		
7. LDR	and opt coupler characteristics		
8. AD5	90 characteristics		
9. Capa	acitive transducer characteristics		
10. Stu	dy of PLC		
11. Imp	elementation of logic gates using PLC		
12. Imp	plementation of flip-flops using PLC		
13. Imp	plementation of timers and counters using I	PLC	
14. To o	construct sequencer using bit logic instruct	ions only	
15. Seq	uential switching of motors using PLC – s	imulation	
16. Tan	k level control using PLC – simulation		
	Estd		
Expected out	tcome.		
Un completion	for the course the student will be able to		
ii. Program	n PLC		
Text Book:			
Hughes .T, Pr	rogrammable Logic Controllers, ISA Pres	s, 1989	