Course co	ode Course Name	L-T-P - Credits	S J 4	Year of
MR/01	Advanced Automation Systems	1-0-01		
Proroquis	ita · NII	4-0-04		2010
Course				
	make students familiar with the automati	on and control tech	nologies	in modern
• 10 ma	nufacturing		mologics	III IIIOdeIII
• To	provide knowledge on the elements of moder	n manufacturing syst	ems	
Syllabus	provide into vicage on the elements of model	i manaraetaring syst		
Automated	d production systems- Manufacturing operation	ns- Industrial contro	l systems.	Automated
Manufactu	uring Systems-Cellular manufacturing-G	oup Technology-	Automated	flexible
manufactu	ring Systems- Advanced inspection system	ns-Lean Production	systems	and agile
manufactu	ring systems.	ITY	5	0
Expected	outcome .	VI I Y		
After com	pleting the course the students will have	/1_1_1_1		
i. kn	ow the functions of the elements of modern ma	anufacturing systems		
ii. kn	ow the modern philosophies of automated ma	nufacturing and the	advanced	automation
sys	stems.	-		
Text Boo	ok:			
1.	Mikell P Groover, Automation, Production	on Systems and C	omputer	-Integrated
Ma	anufacturing, Pearson Education			
Reference	ces:			
1.	Groover , Automation , Production systems an	d CIM , Prentice Hal	l of India	
2. 1	Radhakrishnan, P Subramanian S,CAD/CAM	and CIM ,Wiley East	tern	
3. 1	HMT Mechatronics, TATA Mc Graw Hill			
	Course Pl	an		0
Module	Contents	\cup	Hours	Sem. Exam Marks
Ι	Production system facilities-low medium production-Manufacturing support system production systems-manual labor in pro- automaton principles and strategies-U strategies of Automation and Production Sy Migration strategy-manufacturing industri- manufacturing operations-processing and ass product /production relationships-production product variety-product and part complexi- capabilities of a manufacturing plant	and high quantity as-Automation in oduction systems- SA principle-ten estems-Automation es and products- sembly operations- on quantity and ty-limitations and	10	15%
Π	Elements of an automated system- power Automated process-program of Instruction advanced automation functions-safety monit and repair diagnostics-Error detection and l automation, variables and parameters in pro discrete manufacturing industries-continue control systems-computer process requirements-capabilities of computer com industrial process control-computer process digital control-numerical control and supervisory control-distributed control system	to accomplish the s-control systems- oring-maintenance Recovery-levels of cess industries and ous and discrete control-control trol and levels of monitoring-direct d robotics-PLC- ns	10	15%

FIRST INTERNAL EXAMINATION				
ш	Components of a manufacturing system-production machines- material handling system-computer control system-human resources-classification of manufacturing systems-types of operations performed-number of work stations-automation levels-part or product variety-Type I type II and type III manufacturing systems-manufacturing progress functions- learning curves	9	15%	
IV	Part families-parts classification and coding-features and examples of part classification and coding systems-production flow analysis-cellular manufacturing-composite part concept- machine cell design-application of group technology-survey of industry practice-quantitative analysis in cellular manufacturing-grouping parts and machinery by rank order clustering-arranging machines in GT Cells.	9	15%	
	SECOND INTERNAL EXAMINATION			
V	Inspection metrology-contact and non contact inspection techniques-conventional measuring and gauging techniques- coordinate measuring machines-CMM construction-CMM operation and planning-CMM softwares-CMM applications and benefits-flexible inspection systems-inspection probes on machine tools-surface measurements-stylus instruments- machine vision-image acquisition and digitizing-image processing, digitizing analysis and interpretation- machine vision applications –non contact non optical inspection techniques.	9	20%	
VI	Flexible manufacturing systems-types of FMS-FMS components-workstations-material handling and storage systems-computer control systems-human resources-FMS applications and benefits-FMS planning and implementation issues-FMS planning and design issues-FMS operational issues-lean production-agile manufacturing-market forces and agility-reorganizing the production for agility-manning relationships for agility-agility versus mass production-comparison of lean and agile manufacturing.	9	20%	
	END SEMESTER EXAM			

QUESTION PAPER PATTERN

100 Exam Duration: 3 hours Maximum Marks :

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules

(8 x 5 = 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions (3 x10 = 30 marks)PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

Course c	ode Course Name	L-T-P - Credits	S Int	Year of roduction	
MR40.	3 Nanotechnology	3-0-0-3		2016	
Prerequis	ite : NIL		•		
Course O To To Syllabus Introduction methods- properties composite	 Course Objectives To provide basic knowledge of Nanotechnology and its applications To give an exposure on Nanomaterial and fabrication of Nanostructures Syllabus Introduction to nanotechnology- Nanomaterial- Quantum dots- Nanostructure fabrication methods- Preparation of nanomaterial - Characterization methods- Carbon nanotube preparation, properties and applications - Self assembly of materials- smart materials- Nano fluids- Nano 				
Nano sca lithograph nanotechn sensors- a	le powders- micro and nanofabrication y- soft lithography- Introduction to ME lology and Nano medicines- Nano bots- pplications of nanotechnology	techniques- photo reading MS- NEMS and National targeted drug delivery	sist mate: no electro y- dendrin	rials- Nano onicsbio- ners- Nano	
Expected On compl- i. be ii. aco	d outcome. etion of the course students will familiar with various nano fabrication metho quire knowledge on MEMS, NEMS,CNT, A	ods. FM, SEM,TEM etc			
Text Boo 1. 2. 3. V	Dk: A.K. Bandyopdhyay, <i>Nanomaterials</i> , New ag Nanocomposite science and technology, Pul Nanolithography and patterning techniques i Vood head publishing 2005.	ge international publish ikel M. Ajayan, Wiley n microelectronics, Da	ners – VCH 20 avis G. Bu	005 cknall,	
References: 1. V.S.Muralidharan, A Subramnya, Nano science and Technology Ane books Pvt Ltd 2. Lynn E. Foster, Nanotechnology - Science, Innovations & Opportunity, Pearson, 2012 3. John Mongillo, Nano Technology Greenwood Press					
	Course	Plan			
Module	Contents		Hours	Sem. Exam Marks	
Ι	Introduction to nanotechnology-top down a Approach-Nanomaterial-effects of surface Quantum dots	nd bottom up to volume ratio-	7	15%	
П	Nano structure fabrication methods-Ball methods-Preparation of Nanomaterial lil different type of Nano oxides	milling-CVD- solgel te gold, silver, and	7	15%	
	FIRST INTERNAL EX	AMINATION			
III	Characterisation methods-Scanning Ele Transmission Electron Microscopy, Atomic Carbon nanotube preparation- properties and a	ectron Microscopy, c Force Microscopy- pplications of CNT	7	15%	

IV	Self assembly of materials- self assembled Nano layers- smart materials- Nano fluids- Nano composites- Nano fillers- Nano clays- Nano cluster- Nano wires-applications	7	15%
	SECOND INTERNAL EXAMINATION		
V	Safety issues with Nano scale powders- micro and nanofabrication techniques- photo lithography- photo resist materials- Nano lithography- soft lithography	7	20%
VI	Introduction to MEMS, NEMS and Nano electronics, bio- nanotechnology and Nano medicines, Nano bots, targeted drug delivery, dendrimers- Nano sensors- applications of nanotechnology	7	20%
	END SEMESTER EXAM		

QUESTION PAPER PATTERN

Maximum Marks : 100 PART A: FIVE MARK QUESTIONS Exam Duration:3 hours

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5= 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

(3 x10 = 30 marks)

(2.....

Course co	ode Course Nar	ne	L-T-P - Credit	s Int	Year of roduction
MR40 :	5 Embedded Sys	stems	3-0-0-3		2016
Prerequis	ite : NIL				
Course O • To pro- sys • To em • To toc Syllabus Embedded specific i processors	bjectives make students familiar wit ogramming models, tools for er tem. o give students knowledge on t bedded systems design. expose students to the concep ls and RTOS system, Functional building b system design- Classification nstruction set processors- -Common memory device- Tv	h the architectu nbedded system of he hardware and ts of embedded s lock of embedded n-SOC- Custom General-purpose pes of I/O device	re, hardware and design and implem real time operating system principles, d system- Charact Single-purpose pr processors- Star es - Serial devices	d softward entation o g systems software d eristics- C ocessors- ndard sin - Parallel	e elements, f embedded used for the evelopment hallenges in Application gle-purpose port devices
Expected The stude • the • the • the • the	l outcome. ent will be familiar with concepts of embedded system basic concepts of real time Op design techniques to develop s general purpose operating syst	s berating system de software for embe tems and the real	esign. edded systems time operating syst	ems	
Text Boo 1 1 Mc 2. Ha 3.	k: Rajkamal, " <i>Embedded Systems</i> Graw-Hill Publishing Compan Frank Vahid and Tony <i>rdware/Software Introduction</i> , David E.Simon, "An embedded	– Architecture, F y Ltd., New Delf Givargis, Emb Wiley, 2002. I software primer	Programming and A ni, 2010. Dedded System ", Pearson Educat	Design", T Design: ion Asia 20	[°] ata <i>A Unified</i> 001.
Reference 1. De Pu 2. PH	es: Wayne Wolf, " <i>Computers as osign</i> ", The Morgan Kaufmann blications, 2008. Dainel W. Lewis, <i>Fundament</i> I 2002.	Components: Prin Series in Comput tals of embeddea	nciples of Embedd eer Architecture an software where (ed Compu d Design, C and asso	ter Systems Elsevier embly meet,
		Course Plan	1		0 5
Module	C	ontents		Hours	Sem. Exam Marks
Ι	Embedded system- Functional b Characteristics of embedded s embedded system design- Embed	building block of our system application design des	embedded system- ns- Challenges in n processes	7	15%
II	Classification - Processors in the components - Typical application (SoC) and use of VLSI circuits.	e system - Other h ons - Embedded s	/w units. Software systems on a chip	7	15%

III	Custom Single-purpose processors : Hardware-Combinational Logic- Transistors and logic gates- Basic combinational and Sequential logic design- Custom single purpose processor design and optimization. Application specific instruction set processors- Microcontrollers- Digital signal processors	7	15%
IV	General-purpose processors: Software: Basic architecture- Datapath- Control unit- Memory- Instruction execution- Pipelining- Superscalar and VLIW architectures- Instruction set- Program and data memory space- Registers- I/O- Interrupts- Operating Systems- Standard single-purpose processors: Peripherals-some examples such as Timers- counters- Analog-digital converters.	M ₇	15%
	SECOND INTERNAL EXAMINATION		
V	Common memory devices - Memory selection - Memory map - Internal devices & I/O devices map - Direct memory access Types of I/O devices - Serial devices - Parallel port devices - Sophisticated features - Timer and Counting devices - Advanced serial bus & I/O - High speed Buses - Common types - Advanced Buses.	7	20%
VI	Development tools : Host and Target machines – linker / locators – debugging techniques. S/W Architectures: Round robin-round robin with interrupt – function queue scheduling- RTOS.	7	20%

QUESTION PAPER PATTERN

Maximum Marks : 100 Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules $(8 \times 5 = 40 \text{ marks})$

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

(3 x10 = 30 marks)

2014

Course co	ode Course Name	L-T-P - Credit	s Int	Year of roduction
MR40 7	Autotronics	3-0-0-3		2016
Prerequis	ite : NIL			
Course O • Thi ele	bjectives s course provides basic knowledge on the wor etronic systems in automobiles.	king of automobiles	and the el	ectrical and
Syllabus Automotiv and Ignition hybrid veh and Avoid	re fundamentals: The engine-components-syst on system –Electronic ignition system- Safe nicles - Vehicle Intelligence - mobile robot v ance system-low tire pressure warning system.	ems -Automotive s ety and comfort - ision -object detect	ensors -Fu Electric v ion- collisi	el injection ehicles and on warning
Students	will	III		
acc be be	uire knowledge on the sensors used in vehicle familiar with the various electronic controls us come familiar with advanced comfort and safe	s ed in automobiles ty systems used in a	automobile	S
Text Boo	k:			
1. To: 200	m Denton, Automobile electrical and electroni)4	c systems, BH Publ	lication, Th	ird edition.
Reference	es:			
1. Wi	llium B. Ribbens, Understanding Automoti	ve Electronics - S	sixth edition	on Elsevier
Sci 2. Ro	ence 2003 nald K.Jurgen, Sensors and Transducers - SAE	2003		
3. Jac 4. Ro	k Erjavec, Robert Scharff, Automot <mark>iv</mark> e Techno nald K.Jurgen, Electric and Hybrid-electric yel	ology - Delmar publ hicles - SAE 2002	ications In	c 1992
5. Ich	iro Masaki, Vision-based Vehicle Guidance -	Springer Verlag, Ne	wyork 199	2
6. Jay Pu	Webster, Class Room Manual For Autor	motive Service Ar	nd System	- Delmer
7. Ro	n Hodkinson, John Fenton, Light Weight	Electric/Hybrid Ve	hicle Desi	gn - Read
Ed	ucational and Professional Publications Ltd. 20	001.		0
	Course Pla	n		
Module	Contents 4		Hours	Sem. Exam Marks
I	Automotive fundamentals: The engine-comp -Starting & charging systems operation- Ignit Suspension systems-brakes -ABS - Steering Cruise Control	onents-Drive train ion system- system –Adaptive	7	15%
П	Automotive sensors: introduction- worki sensors- throttle position sensors-manifold mass air flow sensor-engine coolant tem vehicle speed sensors- crankshaft position se oxygen sensors	ng principle of pressure sensor- perature sensors- ensors-exhaust gas	7	15%

FIRST INTERNAL EXAMINATION

III	Fuel injection and Ignition system: Introduction -fuel system components-electronic fuel system-fuel injection-types-throttle body versus port injection-electronic control fuel injection- operation-different types-fuel injectors-idle speed control- continuous injection system-high pressure diesel fuel injection – multi point fuel injection system –Electronic ignition system- operation-types-Electronic spark timing control.	7	15%
IV	Safety and comfort : antilock braking system-traction control system-electric seats- mirrors and sun roofs- central locking and electric windows-cruise control-electric power steering- electronic clutch-electronic suspension system-airbags	7	15%
	SECOND INTERNAL EXAMINATION		
V	Electric vehicles and hybrid vehicles: Introduction-Electric Vehicle development- system layout- basic system components-fuel cell Electric vehicle. Hybrid vehicle: series Hybrid Vehicle - parallel Hybrid Vehicle-CNG Electric hybrid vehicle.	7	20%
VI	Vehicle Intelligence: Introduction -basic structure-vision based autonomous road vehicles-architecture for dynamic vision system -features-applications. An application of mobile robot vision to a vehicle information system-object detection- collision warning and Avoidance system-low tire pressure warning system.	7	20%

QUESTION PAPER PATTERN

Maximum Marks : 100 Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules $(8 \times 5 = 40 \text{ marks})$

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

(3 x10 = 30 marks)

2014

Course code	Course Name	L-T-P - Credits	Year of Introduction		
MR409	Micro Electro Mechanical Systems	3-0-0-3	2016		
Prerequisite : NIL					

Course Objectives

• To impart knowledge in micro machining techniques and Micro Electro Mechanical systems

Syllabus

Micro electro mechanical system – micro fabrication – microsystems and miniaturization-Materials for MEMS - Microsystems packaging- Micro Manufacturing Techniques - Microfabrication special machining - Theory of micromachining- Binder less wheel-Free form optics – Micro sensors: acoustic – Micro actuation - MEMS with micro actuators - Laws of scaling-Applications of MEMS - Future of MEMS

Expected outcome.

On completion of the course the student will be able to understand

- i. the technology for fabrication of MEMS
- ii. the behavior of materials used in MEMS
- iii. the applications of MEMS

Text Books:

- 1. Tai-Ran Hsu MEMS & Microsytems Design and Manufacture, Tata McGraw-Hill publishing company Ltd.
- 2. N. Maluf, an Introduction to Microelectro Mechanical Systems Engineering, Artech House, 2000.

References:

- 1. V.C.Venaktesh, Precision Engineering, Tata McGraw-Hill Publishing Company Limited
- 2. Madou M.J., Fundamentals of micro fabrication, CRC Press, 1997.
- 3. Chang Liu, *Foundation of MEMS*, Illinois ECE Series, Pearson Prentice Hall 2006.

Estd.

Course Plan				
Module	Contents	Hours	Sem. Exam Marks	
Ι	Micro electro mechanical system: MEMS and microsystems – evolution of microfabrication – microsystems and miniaturization- Materials for MEMS - Microsystems packaging.	7	15%	
П	Micro Manufacturing Techniques: Photolithography- chemical Vapour Deposition – Physical Vapour Deposition- Etching Processes-Bulk micro manufacturing- surface micro manufacturing- LIGA process.	7	15%	
FIRST INTERNAL EXAMINATION				

Ш	Micro-fabrication special machining: Laser beam micro machining- Electrical Discharge Machining- Ultrasonic Machining- Electro chemical Machining- Electron beam machining. Clean room-New Materials	7	15%
IV	Mechanical micromachining: Theory of micromachining-Chip formation-size effect in micromachining-microturning- micromilling- microdrilling- Precision Grinding : Partial ductile mode grinding- Binderless wheel-Free form optics.	7	15%
	SECOND INTERNAL EXAMINATION		
V	Microsensors:acoustic- biomedical- chemical- optical- pressure- thermal- Microactuation : actuation using thermal forces- shape memory alloys- piezo electric crystals-electrostatic forces. MEMS with micro actuators: microgrippers - micromotors-microvalves- micropumps.	7	20%
VI	Laws of scaling- Applications of MEMS in various industries : Automobile- defence- healthcare- Aerospace- industry- Future of MEMS	7	20%

QUESTION PAPER PATTERN

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5= 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

Estd.

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

(3 x10 = 30 marks)

Course code	Course Name	L-T-P- Credits	Year	of oduction
ME4	59 FINITE ELEMENT ANALYSIS	3-0-0-3	2	016
	Prerequisite : Nil	-A - A		
Course C	bjectives	AA	1	
1. To le	arn the mathematical background of finite element methods.		1.	
2. To u	derstand the basics of finite element formulation.	A		
3. To p	actice finite element methodologies through structural and heat tra	nsfer probl	ems.	
Syllabus		<i>.</i>		
Introduct	on; Brief history; Review of elasticity; Direct approach;1D b	ar elemen	t; Ana	logous
problems	Beam elements; Plane truss; Coordinate transformations; Interpo	olation fun	ctions;	Shape
functions	Variational methods; Strong and weak form; Rayleigh Ritz m	ethod; FE	E form	lation
elements;	Weighted residual methods; FEA software packages.	ements, is	so para	metric
Expected	outcome			
The stude	nts will be able to			
i. uno	lerstand the mathematical background of FEM .			
ii. sol	ve real life problems using finite element analysis			
Text Boo	ks:			
1. Cha	ndrupatla T R., Finite Element Analysis for Engineering and Tech	n <mark>o</mark> logy, Ur	niversit	y Press,
2004				
2. Hutt	on D V., Fundamentals of Finite Element Analysis, Tata McGraw	-Hill, 2005	0010	
3. Log	an D L., A first course in the Finite Element Method, Thomson-Er	gineering,	2012	
4. Sest	u P., Text Book of Finite Element Analysis, PHI Learning Pvt. Lt	d., 2003		
Referenc	es Books:			
1. Coo	K R D., Malkus D S., Plesha M E., Witt R J., Concepts and Analysi	s of Finite		
Elen	nent Applications, John Wiley & Sons, 1981			
2. Red	ly J N., An introduction to the Finite Element Method, McGraw-1	Hill, 2006		
	Course	-		
	Course	- I		End
Module	Contents		Hours	Sem.
				Exam Morke
				1141 85
	Introduction to Finite Element Method (FEM)- Brief history- Apj	olication		
т	Di FEA- Auvanages and disauvanages.	-Stress	•	15%
1	strain relations- Boundary conditions- Plane stress, plane strain and	nd	2	1370
	axisymmetry.			

	Direct approach-1D bar element- element stiffness- Assembly of elements- properties of [K] matrix- Treatment of boundary conditions-Stress computation.			
п	Analogous problems of torsion, heat conduction and laminar pipe flow. Beam elements- FE formulation-element stiffness matrix- boundary conditions.		20%	
	Plane truss- Element formulation-Co ordinate transformation- Local and global co ordinates- Stress calculations.	4	2070	
	FIRST INTERNAL EXAMINATION	I		
ш	Interpolation functions-Shape functions- Lagrange interpolation- 1D linear and quadratic element	3	15%	
	Variational methods: Functionals- Strong and weak form- Essential and natural boundary conditions.	3	1370	
	Principle of stationary potential energy- Rayleigh Ritz method.	3		
IV	FE formulation using minimization of potential- B matrix- Element matrices for bar element- Consistent nodal loads.	4	20%	
	SECOND INTERNAL EXAMINATION			
V	Higher order elements- Quadratic and cubic elements-Pascal's triangle- Serendipity elements.	3	1.50/	
	Iso parametric elements, Natural coordinates, Area co ordinates- Quadrilateral elements-Jacobian matrix-Gauss quadrature.	5	15%	
VI	Weighted residual method: Galerkin FE formulation. Axially loaded bar- Heat flow in a bar	5		
	Structure of FEA software package. Introduction to Modal analysis, non linear analysis and coupled analysis.	2	15%	
	END SEMESTER EXAMINATION			

Question Paper Pattern

2014

Maximum marks: 100,

The question paper should consist of three parts

Part A

There should be 2 questions each from module I and II Each question carries 10 marks Students will have to answer any three questions out of 4 (3X10 marks = 30 marks)

Part B

There should be 2 questions each from module III and IV Each question carries 10 marks Students will have to answer any three questions out of 4 (3X10 marks =30 marks) Time: 3 hrs

Part C

There should be 3 questions each from module V and VI Each question carries 10 marks Students will have to answer any four questions out of 6 (4X10 marks =40 marks)

Note: Each question can have a maximum of four sub questions, if needed.



Course co	ode Course Name	L-T-P - Credit	s Int	Year of roduction
MR46	Fuzzy Logic Controllers	3-0-0-3		2016
Prerequis	ite : NIL		ŀ	
Course O	bjectives			
• To	provide students an exposure to the basics	of fuzzy logic, neural n	etworks ar	nd the
app	blications of these concepts .			
	ADI ADINI II	LATAN	. A	
Syllabus	AFLADUL	KALAA	VI	
Fuzzy Log	gic – fuzzy sets and membership – Cla	ssical Relations and Fu	zzy Relati	ons - fuzzy
Cartesian	product and composition- Membership	functions - Fuzzy to C	Crisp Con-	versions –
defuzzifica	ation methods- Fuzzy Rule Based System	s – graphical technique	s of infere	ence- Fuzzy
Decision	Making - Fuzzy Control Systems - Arti	ficial Neural Networks	-Back	propagation
Expected	and its variants – Different types of learnin	ig-examples		
Upon com	pletion of this course the student will			
i	be familiar with fundamental of fuzzy	approaches		
ii	. acquire knowledge on fuzzy linguistic	descriptions and their a	nalytical f	orms
iii	• be familiar with the feature of Neural	Networks, types of activ	vation func	tions and
	their classifications			
Text Boo	ks:	5.4		
1. Va	llum B.R and Hayagriva V.R C++, Neural	networks and Fuzzy log	gic, BPB	
Pu	olications, New Delhi, 1996			
2. Tir	nothy J. Ross, Fuzzy Logic with Engineer	ring Applications, McG	raw Hill I	nternational
Ed	ltions			
1 Mi	es: Ilon W.T. Sutton R.S. and Werbos P.I. Ne	ural Networks for contro	MIT Pre	ss 1997
2. Kli	r .G.J and Yuan B.B Fuzzy sets and Fuzzy	logic. Prentice Hall of	India Pvt.	Ltd. New
De	lhi 1997	8 ,		
3. Ko	sko. Neural Networks and Fuzzy systems,	Prentice hall of India P	vt. Ltd. Ne	ew Delhi
199	estd.			
4. Dii	ankov D. Hellendoorn H, Reinfrank M, I	ntroduction to Fuzzy cor	ntrol, Naro	osa
5 7u	rada I M Introduction to Artificial Neural	Systems Jaico Publishir	ng House	New Delhi
199	94	Systems face I donsm	ig mouse,	New Denn
	Course	e Plan		
Module	Contents		Hours	Sem. Exam Marks
	Fuzzy Logic: introduction – uncertaint	ty and imprecision –		
	uncertainty in information – fuzzy set	s and membership –		
Ţ	chance versus ambiguity.	1	7	150/
1	classical sets properties of classical sets	al sets: operations on mapping of classical	/	15%
	sets to functions – fuzzy sets: fuzzy set	operations- properties		
	of fuzzy sets	operations properties		
	Classical Relations and Fuzzy Relations	: Cartesian product –		
II	crisp relations: cardinality of crisp relation	ons- properties of crisp	7	15%
	relations - fuzzy relations: cardinality	of fuzzy relations-		

	operations on fuzzy relations- properties of fuzzy relations-		
	fuzzy Cartesian product and composition		
	FIDET INTERNAL EXAMINATION		
	FIKST INTERNAL EXAMINATION		
	Membership Functions: features of membership functions –		
	standard forms and boundaries – fuzzification – membership		
III	value assignments – membership function generation-	7	15%
	Fuzzy to Crisp Conversions: lambda-cuts for fuzzy sets –		
	lambda cuts for fuzzy relations – defuzzification methods.		
	Fuzzy Rule-Based Systems- graphical techniques of inference-	. A.	
	Fuzzy Decision Making: fuzzy synthetic evaluation $-$ fuzzy	VI	
IV	ordering preference and consensus multipliective decision	7	15%
1 V	ordering – preference and consensus – multi-objective decision	/	1370
	making – ruzzy Bayesian decision method – decision making	ıg	
	under fuzzy states and fuzzy actions.		
	SECOND INTERNAL EXAMINATION		
	Fuzzy Control Systems: review of control system theory -		
• •	simple fuzzy logic controllers –general fuzzy logic controllers	-	2004
V	- special forms of fuzzy logic control system models -	1	20%
	examples of fuzzy control system design		
	Artificial Noural Natworks: Introduction history of noural		
X / I	Aluncial Neural Networks. Introduction – instory of neural $1 + 1 + 1 + 1 + 1 + 1 + 1 + 1 + 1 + 1 $	7	2007
VI	networks – multilayer perceptron –Back propagation algorithm	/	20%
	and its variants – Different types of learning- examples		
END SEMESTER EXAM			

QUESTION PAPER PATTERN

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5= 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

Estd.

	(3 x 10 = 30 marks)
PART C: 15 MARK QUESTIONS	
A quastions uniformly accurring the last two modules	Each quastion can have maximum

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

	(2 x 15 = 30 marks)
PART B: 10 MARK QUESTIONS	
2 optional questions from each of first four modules.	(4 x10 = 40 marks)
PART C: 15 MARK QUESTIONS	
2 optional questions from each of last two modules.	(2 x15 = 30 marks)

Course c	ode Course Name	L-T-P - Credit	s Tnt	Year of roduction	
MR46	3 Bio Mechatronics	3-0-0-3		2016	
Prerequis	ite : NIL		1		
Course O	bjectives				
The course	e enables the students to:				
• un	derstand types of sensors used in biomedical ap	oplications.	_	_	
• be	familiar with various equipment in bio-medica	ll applications and th	ne techniqu	ies of	
dia	gnosis	KALAN			
SyllabusCell structure – electrode – electrolyte interface- electrode potential- electrodes for theirmeasurement- ECG- EEG- EMG -Basic transducer principles – Bio & Nano sensors - Inputisolation- – instrument power supply- Telemetry principles – Bio telemetry-Electrocardiographmeasurements – blood pressure measurement – blood flow measurement – phonocardiography –vector cardiography - Heart lung machine – artificial ventilator – Anesthetic machine – Basicideas of CT scanner – MRI and ultrasonic scanner – Bio-telemetry – laser equipment andapplication – cardiac pacemaker – DC – defibrillator patient safety - electrical shock hazards-Centralized patient monitoring system- computers in medicine – basis of signal conversion anddigital filtering data reduction technique – time and frequency domain technique – ECG Analysis					
ExpectedThe studeni.gaiii.beiii.haText BooAr	nts will n knowledge in medical measurements. able to select appropriate equipments for medi we knowledge on diagnosis and analysis capabi oks: rumugam M., "Bio Medical Instrumentation",	cal applications. lities of biomedical Anuradha agencies l	<u>equipmen</u> Pub., 2002	ts	
Reference 1. 2. Ed 3. Ed 4.	References: 1. Khandpur, R.S., "Handbook of Biomedical Instrumentation", TMH, 1989. 2. Geddes L.A., and Baker, L.E., Principles of Applied Bio-medical Instrumentation, 3rd Edition, John Wiley and Sons, 1995. 3. Cromwell, Weibell and Pfeiffer, Biomedical Instrumentation and Measurements, 2nd Edition, Prentice Hall of India, 1999. 4. Tompkins W L. Biomedical Digital Signal Processing. Prentice Hall of India, 1998.				
	Course Pla	an		Som Exom	
Module	Contents		Hours	Sem. Exam Marks	
I	Cell structure – electrode – electrolyte in potential- resting and action potential – el measurement- ECG- EEG- EMG – mach methods of measurement – three equipment f shooting	terface- electrode ectrodes for their ine description – ailures and trouble	7	15%	
Π	Basic transducer principles Types – sour potentials – resistive- inductive- capaci photoelectric and chemical transducers – the feature applicable for biomedical instrume Nano sensors & application	rce of bioelectric itive- fiber-optic- eir description and entation – Bio &	7	15%	

	FIRST INTERNAL EXAMINATION			
III	Input isolation- DC amplifier- power amplifier- and differential amplifier – feedback- op-Amp-electrometer amplifier- carrier Amplifier – instrument power supply- Oscillagraphic – galvanometric - X-Y- magnetic recorder- storage oscilloscopes – electron microscope – PMMC writing systems – Telemetry principles – Bio telemetry	C amplifier- power amplifier- and differential ack- op-Amp-electrometer amplifier- carrier trument power supply- Oscillagraphic – C-Y- magnetic recorder- storage oscilloscopes 7 15 cope – PMMC writing systems – Telemetry elemetry		15%
IV	Electrocardiograph measurements – blood pressure measurement: by ultrasonic method – plethysonography – blood flow measurement by electromagnetic flow meter cardiac output measurement by dilution method – phonocardiography – vector cardiography	7		15%
	SECOND INTERNAL EXAMINATION			
V	Heart lung machine – artificial ventilator – Anesthetic machine – Basic ideas of CT scanner – MRI and ultrasonic scanner – Bio-telemetry – laser equipment and application – cardiac pacemaker – DC – defibrillator patient safety - electrical shock hazards- Centralized patient monitoring system		7	20%
VI	Introduction – computers in medicine – basis of signal conversion and digital filtering data reduction technique – time and frequency domain technique – ECG Analysis		7	20%

QUESTION PAPER PATTERN

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

Estd 8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules $(8 \times 5 = 40 \text{ marks})$

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

(3 x10 = 30 marks)

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

(2 x 15 = 30 marks)

Course code	Course Name	L-T-P - Credits	Year of Introduction			
MR465	Entrepreneurship	3-0-0-3	2016			
Prerequisite : NIL						

Course Objectives

- To impart knowledge on enterprises and entrepreneurship
- To impart knowledge on the various elements in a business systems

Syllabus

Entrepreneurial perspectives- entrepreneurship and economic development- Characteristics of entrepreneur- Process of business opportunity identification and evaluation- industrial policy-Business- Environment market survey - project report preparation- Process and strategies for starting venture- entrepreneurship in international environment- achievement motivation- Time management creativity and innovation structure of the enterprise- Technology acquisition for small units- financing of project and working capital- break even analysis and economic ratios technology transfer and business

Expected outcome

On completion of this subject students will

- i. acquire knowledge on the techno economic feasibility assessment procedure .
- ii. be able to prepare project proposals
- iii. Know the various forms of finance and support available for entrepreneurs.

Text Books:

1. Pandey G.W., A complete Guide to successful Entrepreneurship, Vikas Publishing 2. Harold Koontz & Heinz Weihrich, Essentials of Management, McGraw hill International

References:

1. Hirich R.D. & Peters Irwin M.P., Entrepreneurship, McGraw Hill

2. Rao T V, Deshpande M V, Prayag Mehta & Manohar S Nadakarni, Developing Entrepreneurship a Hand Book, Learning systems

2014				
Course Plan				
Module	Contents	Hours	Sem. Exam Marks	
I	Entrepreneurial perspectives- understanding of entrepreneurship process- entrepreneurial decision process- entrepreneurship and economic development	7	15%	
II	Characteristics of entrepreneur- entrepreneurial competencies- managerial functions for enterprise- Process of business opportunity identification and evaluation- industrial policy	7	15%	
FIRST INTERNAL EXAMINATION				

III	Business- Environment market survey - project report preparation-study of feasibility and viability of a project assessment of risk in the industry	7	15%
IV	Process and strategies for starting venture- stages of small business growth- entrepreneurship in international environment- entrepreneurship- achievement motivation	7	15%
	SECOND INTERNAL EXAMINATION	1	
V	Time management creativity and innovation structure of the enterprise- planning, implementation and growth- Technology acquisition for small units	7	20%
VI	Formalities to be completed for setting up a small scale uniforms of organizations for small scale units-financing of project and working capital-venture capital and other equity assistance available- break even analysis and economic ratios technology transfer and business	7	20%

QUESTION PAPER PATTERN

Maximum Marks : 100

Exam Duration:3 hours

PART A: FIVE MARK QUESTIONS

8 compulsory questions –1 question each from first four modules and 2 questions each from last two modules (8 x 5= 40 marks)

PART B: 10 MARK QUESTIONS

5 questions uniformly covering the first four modules. Each question can have maximum of three sub questions, if needed. Student has to answer any 3 questions

 $(3 \times 10 = 30 \text{ marks})$

PART C: 15 MARK QUESTIONS

4 questions uniformly covering the last two modules. Each question can have maximum of four sub questions, if needed. Student has to answer any two questions

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(2 x15 = 30 marks)

Course code	Course Name	L-T-P - Credits	Year of Introduction		
**451	Seminar and Project Preliminarv	0-1-4-2	2016		
	Prereguisite : Nil				
Course Object	tives				
• To deve	elop skills in doing literature survey, techn	ical presentation and rep	port preparation.		
To enab	ble project identification and execution of I	oreliminary works on fin	nal semester		
project		F 1 T 1 1 1			
Course Plan	API ARDI II I	CALAM			
Seminar: Each	student shall identify a topic of current re	elevance in his/her brand	ch of engineering,		
get approval of	f faculty concerned, collect sufficient lite	erature on the topic, stu	dy it thoroughly,		
prepare own re	port and present in the class.	UICAL			
Project prelim	unary:	Former annoine the same (a	at avaading four		
students) The	tudents can do the project individually al	Form project team (n	ot exceeding four		
the project pro	prosal before the assessment board (ex	cluding the external e	upervisor. Fresenic vpert) and get it		
approved by the	e board	cruding the external e	xpert) and get it		
The preliminar	w work to be completed: (1) Literature s	survey (2) Formulation	of objectives (3)		
Formulation of	hypothesis/design/methodology (4) Form	nulation of work plan (5) Seeking funds		
(6) Preparation	of preliminary report	1	ý		
Note: The same	e project should be continued in the eighth	n semester by the same	project team.		
Expected out	come.				
The students w	ill be able to				
i. Analyse	e a current topic of professional interest an	d present it before an au	dience		
ii. Identify	an engineering problem, analyse it and p	ropose a work plan to so	olve it.		
Evaluation	· 50 montrs				
(Distribution)	. 50 marks for the seminar is as follows: i. P	recontation : 10% ii A	bility to onewar		
questions · 30	% $\&$ iii Report : 30%)	resentation . 40% II. A	Unity to answer		
Project prelim	inary · 50 marks (Progress ex	valuation by the supervi	sor \cdot 40% and		
progress evalu	ation by the assessment board excluding e	external expert : 60%. T	wo progress		
evaluations, n	nid semester and end semester, are mandat	ory.)	1 0		
Note: All eval	uations are mandatory for course completion	on and for awarding the	e final grade.		
2014					
	2014				

Course code	Course Name	L-T-P - Credits	Year of	
MR431	Mechatronics Lab	0-0-3-1	2016	
Prerequisite ·	Nil	0-0-5-1	2010	
Course Object	tivos			
	uves vide hands on experience on the worki	ng of hydraulic and nn	eumetic controls	
speed c	ontrol and PID controllers	ing of injurautic and ph	culture controls,	
• To imp	art proficiency in programming of robots			
 To imp 	art knowledge on virtual instrumentation a	nd vision systems		
· · · · · · · · · · · · · · · · · · ·	art knowledge on virtual instrumentation a	nd vision systems		
List of Exercis	ses/Experiments :	CICAL		
	IEUNINULU	UICAL		
1. Design	and assembly of pneumatic/hydraulic kit	ITV		
2. Study c	of different type of pneumatic and hydrauli	c valve.		
3. Study	of reciprocating movement of double ac	ting cylinder using pro-	eumatic direction	
control	valve.			
4. Speed c	control stepper and servo motor using micr	o processor kit.		
5. Program	nming Robot (Pick and place robot)			
6. Sensors	s for automotives			
7. 1001 cc	ondition monitoring using sensors.			
8. PID Co	introller			
9. Automa 10. Virtual	Instrumentation			
	Data acquisition			
a. h	Image acquisition			
C.	Stepper and servo control device			
d.	Signal conditioning of strain gauge LV	DT. Thermocouple, pre	essure transducer.	
G	etc	e i, inclinice cupie, più	issure transactor,	
11. A/D an	d D/A conversion		•	
12. Machin	e Vision system			
13. Study of robot end effectors				
Expected outcome.				
The students will be able to				
 Develop pneumatic circuits for automating various operations 				
 Program 	n a robot for a pick and place operation			
 Prescril 	be sensors for monitoring and control oper	ations		

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Acquire knowledge on analog and digital data convertors